

DecentLAB



## DL-LID DATASHEET

LASER DISTANCE / LEVEL SENSOR FOR LORAWAN®

## FEATURES

LoRaWAN®-enabled optical distance measurement sensor.

Measurement range: 0 ... 40 m, depending on the reflectivity and shape of the target.

Compatible with LoRaWAN® networks of any provider.

Place and measure: no setup required.

Configurable via command line interface and downlink command interface.

Unattended real-time monitoring for several years without replacing batteries.

Robust polycarbonate enclosure: weatherproof, impact-, UV-resistant (IP67).

Standard alkaline (C-type) batteries.

CE compliant, Radio Equipment Directive (RED) 2014/53/EU.

## APPLICATIONS

Outdoor remote monitoring.

Generic ranging and proximity monitoring.

Snow level monitoring.

Water level monitoring.

Flood monitoring.

Presence detection.

## DESCRIPTION

The device DL-LID measures the distance between the sensor head and the target. The measurement principle is based on infrared laser pulses which are transmitted by the sensor and reflected back from the target object. Using the time of flight of the laser pulses and the known speed of light, the sensor computes the traveling distance and thus the distance to the target.

For each measurement, the device captures N distance readings (samples). By default, N = 10.<sup>1</sup> From these N samples, a set of statistical values is computed: average distance, minimum, maximum, median, 10<sup>th</sup>, 25<sup>th</sup>, 75<sup>th</sup>, 90<sup>th</sup> percentiles and the most frequent value. These statistical values are transmitted, as well as the number of samples (N), the total acquisition time and the battery voltage. The knowledge of the statistics of the distance samples allows the user to estimate the distance with greater accuracy and to evaluate the quality and uncertainty of the measurement.

The number of acquired samples can be configured using the device configuration interfaces (see Section “Device configuration”). The respective commands are

- `set param 4 <N>` set number of samples,  $N_{\min} = 0$ ,  $N_{\max} = 1024$ , default:  $N = 10$ ;<sup>1</sup>
- `get param 4` get number of samples.

Sensor data are transmitted in real-time using LoRaWAN<sup>®</sup> radio technology. LoRaWAN<sup>®</sup> enables encrypted radio transmissions over long distances while consuming very little power. The user can obtain sensor data through Decentlab’s data storage and visualization system, or through the user’s own infrastructure. Visit [www.decentlab.com](http://www.decentlab.com) for more information about Decentlab’s data cloud service.

## DEVICE VARIANTS

Name	Variant
DL-LID-001	001

<sup>1</sup> Firmware versions 1.5.8 and later: N = 10; previous versions: N = 100.

# DEVICE SPECIFICATIONS

## DEVICE LOGGING FUNCTION

Sampling interval	10 min (configurable through the user interfaces)
Data upload interval	10 min (configurable through the user interfaces)
Reported sensor data	Distance: statistics of N samples: <ul style="list-style-type: none"> <li>• average, minimum, maximum distance;</li> <li>• median (50<sup>th</sup> percentile);</li> <li>• 10<sup>th</sup>, 25<sup>th</sup>, 75<sup>th</sup>, 90<sup>th</sup> percentiles;</li> <li>• most frequent distance value;</li> <li>• number of samples N (default: N = 10);</li> <li>• total acquisition time.</li> </ul>
	Battery voltage

## DISTANCE

Operating principle	Laser-based time-of-flight distance measurement
Measurement range	0 ... 40 m (with target reflectivity of 70 %)
Resolution	10 mm (single sample) 1 mm (average of N samples)
Accuracy < 2 m, single sample	±50 mm Note: Nonlinearity is present below 1 m.
Accuracy ≥ 2 m, single sample	±25 mm
Accuracy using multiple samples	Better accuracy is achieved by capturing N samples and evaluating statistical data, e.g. the average of N samples.

## RADIO / WIRELESS

Wireless technology	LoRaWAN <sup>®</sup>
Wireless security	AES-128 data encryption
LoRaWAN <sup>®</sup> device type	Class A end-device
Supported LoRaWAN <sup>®</sup> features	OTAA, ABP, ADR, adaptive channel setup
Wireless range	> 10 km (line of sight <sup>2</sup> ), approx. 2 km (suburban)
RF transmit power	14 dBm (25 mW)
Effective radiated power	11.9 dBm maximum <sup>3</sup>
Receiver sensitivity	-146 dBm <sup>4</sup>
Frequency bands	868 MHz (EU version), 915 MHz (US, AS, AU versions) <sup>5</sup>
Antenna	Integrated omnidirectional antenna featuring a near-perfect radiation pattern <sup>3</sup>

<sup>2</sup> Decentlab reports successful transmissions over 56 km distance and more

<sup>3</sup> See Appendix A: Antenna performance

<sup>4</sup> Specified by radio chip vendor

<sup>5</sup> Contact us for region specific options

## POWER SUPPLY

Internal battery type	2 × alkaline C batteries (LR14)			
Power consumption (average)	≤ 0.5 mW (10 min interval)			
Battery lifetime estimation <sup>6</sup>	N samples	Interval	SF	Lifetime
	10	10 min	SF7	8.3 years
	10	10 min	SF12	3.2 years
	10	60 min	SF7	14.2 years
	10	60 min	SF12	9.8 years
	100	10 min	SF7	3.9 years
	100	10 min	SF12	2.2 years
	100	60 min	SF7	10.7 years
	100	60 min	SF12	8.0 years

## OPERATING CONDITIONS

Temperature	-20 ... 50 °C
Humidity	0 ... 100 % RH

## MECHANICAL SPECIFICATIONS

Transmitter dimensions	135 × 81 × 70 mm (not including sensor / cable)
Sensor dimensions	L × W × H: 40.2 × 55 × 35 mm
Transmitter enclosure rating	Polycarbonate; weatherproof, impact-, UV-resistant (IP66/IP67). Pressure equalizer plug with PTFE membrane (IP68). Sensor head: IPX7
Sensor rating	IPX7
Total weight	440 g including batteries and sensor (310 g without batteries)
Cable length	0.15 m

<sup>6</sup> Including alkaline battery self-discharge of 3.6 % per year (conservative estimation); battery capacity: 20000 mWh.

## OPERATING INSTRUCTIONS

The product usually requires no user interaction. If you open the enclosure, e.g. in order to replace the batteries, unscrew the four plastic screws and carefully open the lid.

**CAUTION:** Make sure the sensor unit does not drop out of the enclosure while opening! Do not touch the electronic components and sensors!

**NOTE:** When closing the lid, make sure the lid is fitted the right way, so that the enclosure is properly sealed: A little nose in the enclosure fits a notch in the lid and vice versa.

## REPLACING BATTERIES

Insert 2 high-quality alkaline C batteries (LR14) into the battery holder on the back side of the sensor unit. The device operates until the battery voltage drops to 2.0 V. Always replace both battery cells with two identical fresh batteries.

## USER BUTTON AND LEDS

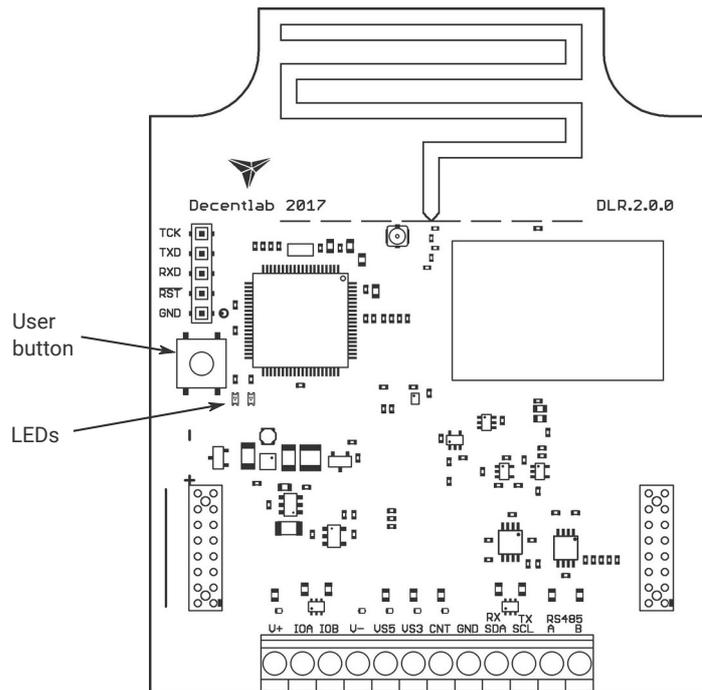


Illustration 1: Sensor unit showing the user button and LEDs. The battery holder is on the back side of the sensor unit.

## OPERATING MODES

The device has four operating modes:

- Reset: System (re-)start; both LEDs fade in and out.
- Active mode (ON): Periodic measurements and data transmissions; green LED flashes for each measurement.
- Sleep mode (OFF): No measurements and data transmissions (power save mode, for shelf storage). LEDs are off.
- Test mode: Measurements and data transmissions at fastest possible rates; blue LED is on.  
NOTE: Use only momentarily, e.g. for testing the sensor or the wireless connection. The device will switch automatically to active mode after 20 minutes.

### SWITCHING BETWEEN OPERATING MODES

The user button allows to switch between the operating modes as shown in Illustration 2 and Illustration 3. To perform a device reset, switch to sleep mode first (if necessary) by pushing and holding the button for 3 seconds until the LEDs flash three times; wait 3 seconds; then push and hold the button for 3 seconds until the LEDs fade in and out. To switch between active and test mode, push the button for 1 second (blue LED on / off). If the blue LED is off, the device is in active or sleep mode. If the blue LED is on, the device is in test mode.

HINT: To check whether the device is active or in sleep mode (on or off), push the button twice; if the blue LED goes on and off, the device is in active mode; otherwise, the device is in sleep mode.

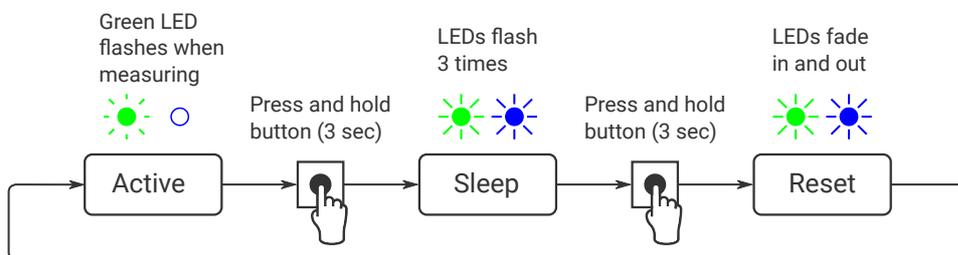


Illustration 2: Switching between active and sleep mode (switch off / on, reset).

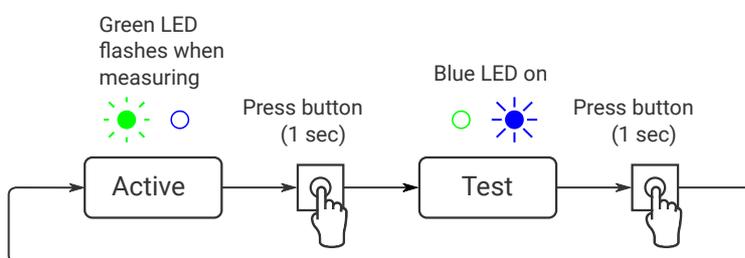


Illustration 3: Switching between active and test mode.

## MEASUREMENT CYCLE (ACTIVE MODE)

During the active mode, the device periodically reads the sensors with sampling period  $T_s = 10$  minutes (default, configurable). When the send period  $T_{TX} = n \cdot T_s$  (default:  $n = 1$ , configurable) has expired, the device computes the average of the collected sensor values (at most 20 values). After a random delay of 0 ... 8 seconds, the device transmits the aggregated sensor data. If the device has not yet joined the LoRaWAN® network, it will try to join until it succeeds (maximum 3 attempts per sampling period). Afterwards, it will transmit the data (TX data). Following the data transmission, two receive slots are opened (RX1 and RX2). During these time slots, the device is ready to receive data from the network (downlink messages) as defined in the LoRaWAN® specification.

As shown in the diagrams, the device is idle most of the time. During the idle time, the current consumption is extremely low.

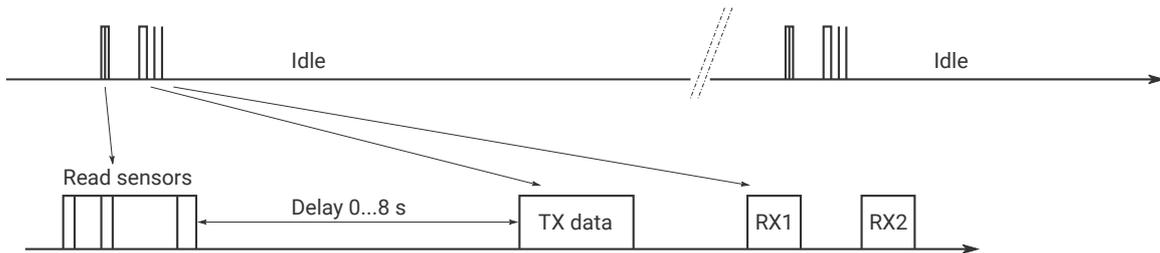


Illustration 4: Device activity during the active mode.

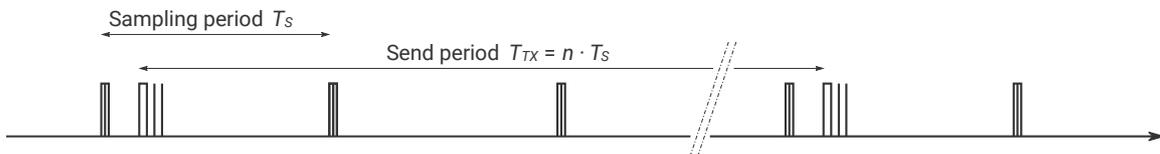


Illustration 5: Sampling period vs. send period. Default:  $T_s = 10$  min,  $T_{TX} = 1 \cdot 10$  min = 10 min.

## LED SIGNALING (ACTIVE MODE)

- Read sensors: green LED flashes once.
- Data sent successfully: green LED flashes 2 times.
- Data could not be sent: green LED flashes 4 times.

## DEVICE CONFIGURATION

The user can configure a rich set of device parameters, such as sampling interval, LoRaWAN® data rate, ADR settings and many more. If desired, the parameter settings can be stored permanently in the internal non-volatile memory. The user can configure the device via two interfaces:

- Command line interface: via a serial cable (UART – USB) connected to a computer.
- Downlink command interface: over the air using LoRaWAN® downlink messages.

For a full description of the command line interface and the downlink command interface, please find the specific documents on [www.decentlab.com/support](http://www.decentlab.com/support).

# MOUNTING INSTRUCTIONS

Prefer a mounting location which is protected against rain and direct sun radiation.

For best radio performance, install the device upright with the cable towards ground; ideally, in such a way that the device lid faces roughly in the direction of the next gateway. Also, the higher above ground, the better. Avoid metallic objects close to the device.

The housing includes 4 threaded bushes (M4) in a 90 × 60 mm rectangle (see Illustration 6). This enables easy installation using standard M4 bolts.

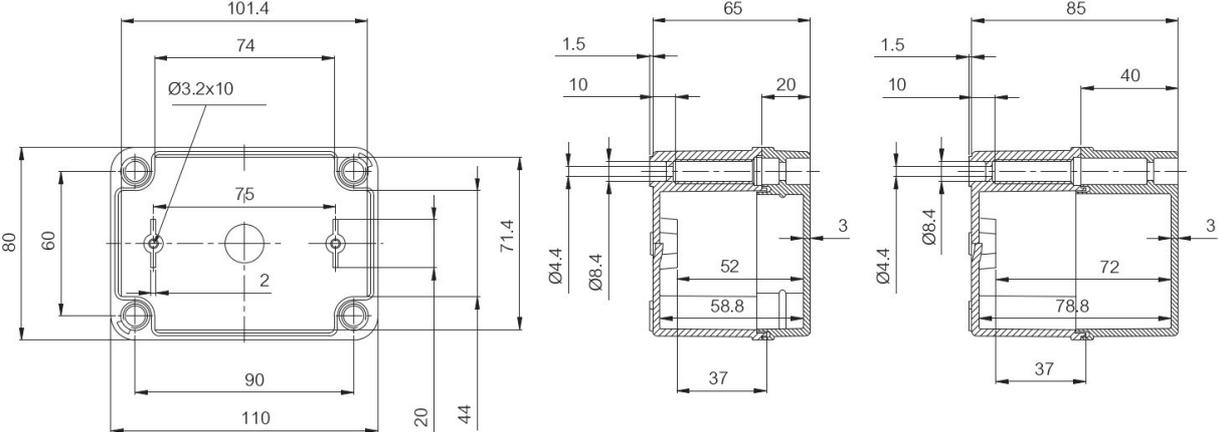


Illustration 6: Housing dimensions (in mm). Note: Drawing not including cable gland and sensor.

## ORDERING INFORMATION

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REFERENCE	VERSION	REGION (LORAWAN®)
DL-LID-001-EU868	001	Europe
DL-LID-001-US915	001	North America
DL-LID-001-AS923	001	Asia
DL-LID-001-AU915	001	Australia, South America

Other options: contact us

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## SENSOR DATA MESSAGE FORMAT

Message:

Header	Sensor 0 data (optional)	Sensor 1 data (opt.)	...	Sensor 15 data (opt.)
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- Message length is variable, depending on which sensor data are included. Minimum length is 5 bytes (header only). Maximum length is 5 bytes + all sensor data (see below).
- Integers are big endian: MSB first byte, LSB last byte.

Header:

Version	Device ID	Flags
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- Version: 1 byte; version = 2 for current protocol version.
- Device ID: 2 bytes; 0...65535.
- Flags: 16 bits: flag 15 | flag 14 | ... | flag 0 (LSB).
- The flags indicate, if data of the respective sensors are included in the message or not:  
Flag n == 1: sensor n data included; flag n == 0: not included.

## DECODER SOFTWARE

For message decoder software, please go to <https://www.decentlab.com/support>, where you find code examples in JavaScript and other programming languages.

## DETAILS

FIELD	PARAMETER NAME	TYPE	CONVERSION	UNIT
Header	Version	uint8		
Header	Device ID	uint16		
Header	Flags	uint16		
Sensor 0	Distance: average	uint16	x	mm
Sensor 0	Distance: minimum	uint16	x	mm
Sensor 0	Distance: maximum	uint16	x	mm
Sensor 0	Distance: median	uint16	x	mm
Sensor 0	Distance: 10 <sup>th</sup> percentile	uint16	x	mm
Sensor 0	Distance: 25 <sup>th</sup> percentile	uint16	x	mm
Sensor 0	Distance: 75 <sup>th</sup> percentile	uint16	x	mm
Sensor 0	Distance: 90 <sup>th</sup> percentile	uint16	x	mm
Sensor 0	Distance: most frequent value	uint16	x	mm
Sensor 0	Number of samples	uint16	x	
Sensor 0	Total acquisition time	uint16	x / 1.024	ms
Sensor 1	Battery voltage	uint16	x / 1000	V

## EXAMPLE 1 (ALL SENSOR DATA INCLUDED)

Message (hex):

**0211c90003119b117611bc119e118a119411a811a81194006401990abd**

<b>02</b>	Version	= 2	
<b>11c9</b>	Device ID	= 4553	
<b>0003</b>	Flags	= 0b0000000000000011	
<b>119b</b>	Distance: average	= 4507	mm
<b>1176</b>	Distance: minimum	= 4470	mm
<b>11bc</b>	Distance: maximum	= 4540	mm
<b>119e</b>	Distance: median	= 4510	mm
<b>118a</b>	Distance: 10th percentile	= 4490	mm
<b>1194</b>	Distance: 25th percentile	= 4500	mm
<b>11a8</b>	Distance: 75th percentile	= 4520	mm
<b>11a8</b>	Distance: 90th percentile	= 4520	mm
<b>1194</b>	Distance: most frequent value	= 4500	mm
<b>0064</b>	Number of samples	= 100	
<b>0199</b>	Total acquisition time	= 399	ms
<b>0abd</b>	Battery voltage	= 2.749	V

## EXAMPLE 2 (ONLY BATTERY VOLTAGE)

Message (hex):

**0211c900020abd**

<b>02</b>	Version	=	2	
<b>11c9</b>	Device ID	=	4553	
<b>0002</b>	Flags	=	0b0000000000000010	
----	Distance: average	=	---	mm
----	Distance: minimum	=	---	mm
----	Distance: maximum	=	---	mm
----	Distance: median	=	---	mm
----	Distance: 10th percentile	=	---	mm
----	Distance: 25th percentile	=	---	mm
----	Distance: 75th percentile	=	---	mm
----	Distance: 90th percentile	=	---	mm
----	Distance: most frequent value	=	---	mm
----	Number of samples	=	---	
----	Total acquisition time	=	---	ms
<b>0abd</b>	Battery voltage	=	2.749	V

## DECLARATION OF CONFORMITY

We,

Decentlab GmbH  
Überlandstrasse 129  
8600 Dübendorf  
Switzerland



declare under our own responsibility that the product

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Reference	Name
<b>DL-LID-xxx-EU868</b>	<b>Laser Distance / Level Sensor for LoRaWAN®</b>

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to which this declaration refers conforms with the relevant standards or other standards documents

- EN 300 220-1 V3.1.1: 2017-02
- EN 300 220-2 V3.1.1: 2017-02
- EN 301 489-1 V2.2.0: 2017-03
- EN 301 489-3 V2.1.1: 2017-03

According to

- Radio Equipment Directive (RED) 2014/53/EU
- Electromagnetic Compatibility (EMC) Directive 2014/30/EU

Dübendorf, 12. September 2018

Reinhard Bischoff, Managing Director

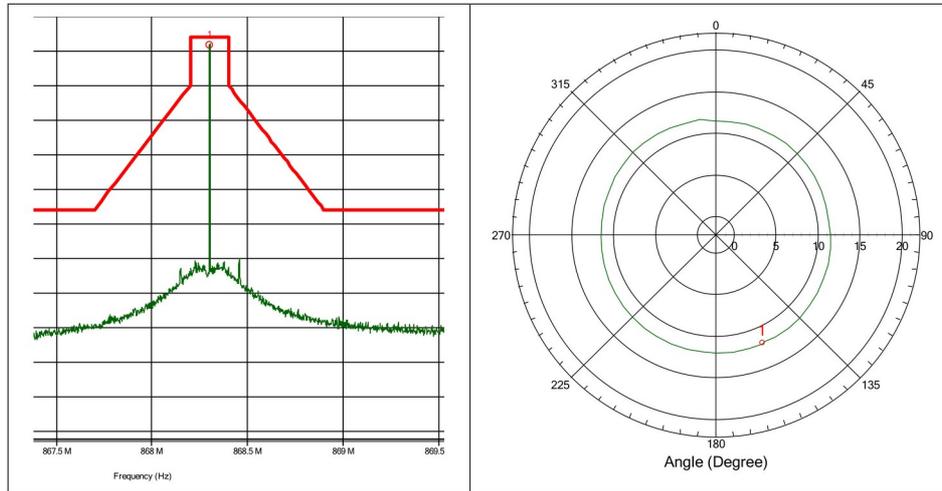
# APPENDIX A: ANTENNA PERFORMANCE

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**Measurement Results:**

<b>EUT</b>	DLR1-LP8		
<b>Test performed</b>	Effective radiated power (ERP)		
<b>Verdict, Test</b>	Pass		
<b>Modification</b>	None		
<b>Mode of operation</b>	Transmitter mode		
<b>Test date, time</b>	13.06.2018 09:37:06		
<b>Antenna height</b>	1.30 m	<b>Antenna polarization</b>	Vertical
<b>EUT position</b>	0 to 360 Degree	<b>Antenna distance</b>	3 m
<b>Measurement settings</b>	Radimantion Version: 2017.1.6, RBW: 1 kHz, VBW: 300 kHz, Sweep time: Auto [120 ms], Step freq: Linear: 250 Hz steps, Attenuator: Auto [10 dB], Internal preamp: 20 dB, Measure time: 10 ms, Measurement equipment: TP_RE_30M-1G_ETSI_Ver		



**Detected peaks**

Peak Number	Frequency	Peak	Peak Difference	Status	Angle	Height	Polarization
1	868.302 MHz	11.9 dBm	-2.14 dB	Pass	157 Degree	1.3 m	Vertical

**Limits:**

ETSI EN 300 220-2, Table C.1 OFB: 863 MHz to 870 MHz <= 0.1% duty cycle or polite spectrum access	<b>25 mW e.r.p</b>  (14 dBm)
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## DISCLAIMER

Specifications and information in this document are subject to change without notice.

Decentlab products are not warranted or authorized for use as critical components in medical, life-saving, or life-sustaining applications, or other applications where a failure would reasonably be expected to cause severe personal injury or death.

## CONTACT INFORMATION

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